

CLASS

the Cosmological Linear Anisotropy Solving System¹



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¹ code developed by Julien Lesgourgues & Thomas Tram plus many others

Lecture 3: coding with `class`

- 1 overall structure of `class`
- 2 dynamical indexing rules
- 3 input parameters
- 4 error management rules
- 5 adding features

Overall structure of `class`

In `CLASS`, what is a `module`?

- a file `include/xxx.h` containing some declarations
- a file `source/xxx.c` containing some functions
- each module is associated with a structure `xx`, containing all what *other* modules need to know, and nothing else
- some fields in this structure are filled in the `input.c` module (input parameters relevant for this module)
- all other fields are filled by a function `xxx_init(...)`
- “executing a module” \equiv calling `xxx_init(...)`



In `include/background.h`: localise struct `background`
In `source/background.c`: localise `background_init()`

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List of structures associated to modules:

module	structure	ab.	*	main content
--------	-----------	-----	---	--------------

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and harmonic spectra are given by $C_l^{ij} = 4\pi \int \frac{dk}{k} \mathcal{P}(k) \Delta_l^i(k) \Delta_l^j(k)$.

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<code>output.c</code>	output	op	pop	description of output format

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Each module contains:

- a function `xxx_init(...)` filling the structure `xx`
- a function `xxx_free(...)` freeing all the memory allocated to this structure
- some functions `xxx_external_1(...)`, ..., `xxx_external_n(...)` that can be called from other modules (e.g. to read correctly or interpolate the content of the structure `xx`)
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Following order always respected in `xxx.c`:

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Remark: a module in the `CLASS` code is very similar to a “class” in `C++`. We enjoy the structure of `C++` with the speed and readability of `C`.

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Count number of external and internal functions in `source/background.c`:
Search “`int background_`” starting from top

Overall structure of `class`

The `main()` function of `CLASS` located in `main/class.c` could only contain:

```
int main() {
    input_init_..(.., ppr, pba, pth, ppt, ptr, ppm, psp, pnl, ple, pop);
    background_init(ppr, pba);
    thermodynamics_init(ppr, pba, pth);
    perturb_init(ppr, pba, pth, ppt);
    primordial_init(ppr, ppt, ppm);
    nonlinear_init(ppr, pba, pth, ppt, ppm, pnl);
    transfer_init(ppr, pba, pth, ppt, pnl, ptr);
    spectra_init(ppr, pba, ppt, ppm, pnl, ptr, psp);
    lensing_init(ppr, ppt, psp, pnl, ple);
    output_init(pba, pth, ppt, ppm, ptr, psp, pnl, ple, pop)
    /* all calculations done, free the structures */
    lensing_free(ple);
    spectra_free(psp);
    transfer_free(ptr);
    nonlinear_free(pnl);
    primordial_free(ppm);
    perturb_free(ppt);
    thermodynamics_free(pth);
    background_free(pba);
}
```

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- Example: we want to define the indices of a vector of background quantities (stored in the background table).
- We choose an abbreviation of 2 letters for these indices, `_bg_`.
- Then we declare all possible indices `index_bg_<blabla>` in `include/background.h` (more precisely, inside the structure `background`, because these indices are necessary for manipulating the background table).

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- Example: we want to define the **indices of a vector of background quantities** (stored in the background table).
- We choose an abbreviation of 2 letters for these indices, `_bg_`.
- Then we declare all possible indices `index_bg_<blabla>` in `include/background.h` (more precisely, inside the structure `background`, because these indices are necessary for manipulating the background table).
- We also declare **flags** saying whether these indices need to be defined or not.

Dynamical indexing rules in `class`

In `include/background.h`:

```
struct background {
    /** input parameters with assigned in the input module*
     */
    double Omega0_cdm;
    ...
    /** flags and indices */
    int has_cdm;    // can take values _TRUE_ or _FALSE_
    ....

    int index_bg_rho_cdm;
    ...

    int bg_size;

    /** interpolation table */
    double * background_table;
}
```

Dynamical indexing rules in `class`

In `source/background.c`, the function `background_indices()` called at the beginning of `background_init()` assigns numerical value to indices, that the **user will never need to know** (quantities always written symbolically as `y[pba->index_bg_rho_cdm]`)

```
int background_indices(pba,...) {
    /* initialize all flags */
    if (pba->Omega0_cdm != 0.)
        pba->has_cdm = _TRUE_;
    ...
    /* initialize all indices */
    index_bg=0;
    class_define_index(pba->index_bg_rho_cdm,
                      pba->has_cdm,
                      index_bg,
                      1);
    class_define_index(pba->index_bg_rho_fld,
                      pba->has_fld,
                      index_bg,
                      1);
    ...
    pba->bg_size = index_bg;
}
```

Dynamical indexing rules in `class`

This logic is followed everywhere for all groups of indices! Examples:

- in `background.c`: `index_bg_...` for all background variables
- in `background.c`: `index_bi_...` subset of backg. var. integrated over time
- in `thermodynamics.c`: `index_th_...` for all thermodynamics variables
- in `perturbations.c`: `index_pt_...` perturbation var. integrated over time
- in `perturbations.c`: `index_mt_...` metric perturbations
- in `perturbations.c`: `index_md_...` list of modes (scalar, vector, tensor)
- in `perturbations.c`: `index_ic_...` list of initial conditions (AD, CDI, NID...)
- in `perturbations.c`: `index_tp_...` list of type of required source
(temperature, polarisation, matter fluctuation...)
- in `perturbations.c`: `index_ap_...` list of approximations that may be used
- etc. etc.



Check in your `include/*.h` files!

Input management in `class`

Terminal

Python wrapper

`file xxx.ini`



`input_init_from_argument(...)`

(parser)



`struct file_content fc;` (all parameter names/values stored as arrays of strings)



`input_init(...)`



`input_read_parameters(...)`

(assign all default values + interpret input + update some parameters)



relevant parameters only get stored in the structures of each module

`.set(...)`



For special parameters requiring a **shooting method**: repeated calls of `input_read_parameters(...)` from `input_init(...)` until shooting target is met.

Input management in class

For normal parameters (no shooting): example of CDM density:

```
/** - Omega_0_cdm (CDM) */
class_call(parser_read_double(pfc, "Omega_cdm", &param1, &
    flag1, errmsg),
    errmsg,
    errmsg);
class_call(parser_read_double(pfc, "omega_cdm", &param2, &
    flag2, errmsg),
    errmsg,
    errmsg);
class_test(((flag1 == _TRUE_) && (flag2 == _TRUE_)),
    errmsg,
    "In input file, you can only enter one of
    Omega_cdm or omega_cdm, choose one");
if (flag1 == _TRUE_)
    pba->Omega0_cdm = param1;
if (flag2 == _TRUE_)
    pba->Omega0_cdm = param2/pba->h/pba->h;
```

Input management in `class`

For **shooting** parameters, establish mapping between *target parameter*, *unknown parameter* and *level*. Currently:

target parameter	unknown parameter	level
$100 \times \theta_s$	h	thermodynamics
σ_8	A_s	spectra
Ω_{dcdm}	$\rho_{\text{dcdm}}^{\text{ini}}$	background
...

... plus a few others (alternative parametrizations of decaying CDM, quintessence parameters).

If you need to add such parameters: see how it is done e.g. for `100*theta_s` and replicate the structure!

Error management rules in `class`



Run with an input file containing only

```
omega_b = 0.07
```

Error management rules in `class`

By following a few general rules, we get automatically some very informative error messages like:

```
Error in thermodynamics_init
=>thermodynamics_init(L:292) :error in
  thermodynamics_helium_from_bbn(ppr,pba,pth);
=>thermodynamics_helium_from_bbn(L:1031) :condition (omega_b
  > omegab[num_omegab-1]) is true; You have asked for an
  unrealistic high value omega_b = 7.e-02. The
  corresponding value of the primordial helium fraction
  cannot be found in the interpolation table. If you
  really want this value, you should fix YHe to a given
  value rather than to BBN
```

We only wrote the piece starting with “You have asked...”. All the rest was generated automatically by the code. This follows from following everywhere **5 rules**.

Error management rules in `class`

Rule 1:

All functions are of type `int`, and return either `_SUCCESS_` or `_FAILURE_` (defined internally in `include/common.h`: `#define _SUCCESS_ 0` , `#define _FAILURE_ 1`)

```
int function(input, &output) {  
    ...  
    if (something goes wrong) return _FAILURE_;  
    ...  
    return _SUCCESS_;  
}
```

Error management rules in `class`

Rule 2:

All functions are called with the macro `class_call(.,.,.)` (all macros `class_xxx(...)` are defined in `include/common.h`):

```
class_call(function(input, &output),
            error_message_from_function,
            error_message_output);
```

This is simply a short-cut for

```
if (function == _FAILURE_) {
    ErrorMsg Transmit_Error_Message;
    sprintf(Transmit_Error_Message, "%s(L:%d) : error in %s;\n
        n=>%s", __func__, __LINE__, #function,
            error_message_from_function);
    sprintf(error_message_output, "%s", Transmit_Error_Message
        );
    return _FAILURE_;
}
```

Error management rules in `class`

Rule 3:

Each of the 9 main structures `xx` has a field called `error_message`. Any function in the module `xxx.c` is called `xxx_something()` and writes its error message in `xx.error_message` (if `pxx` is a pointer to `xx`, in `pxx->error_message`).

So if we are in `perturb_init()` and we call `perturb_indices()` we write:

```
class_call(perturb_indices(..., ppt),
           ppt->error_message,
           ppt->error_message);
```

But if we are in `perturb_init()` and we call `background_at_tau()` we write:

```
class_call(background_at_tau(..., pba),
           pba->error_message,
           ppt->error_message);
```

Error management rules in `class`

Rule 4:

Whenever an error could occur, we first write a test with the macro

```
class_test(.,.,.):
```

```
class_test(condition, error_message, "Some text");
```

or

```
class_test(condition, error_message, "Some text and numbers  
%d %e", n, x);
```

Example:

```
class_test(num_points == 0,  
           ppt->error_message,  
           "this might be caused by ...");  
step = (max-min)/((double)num_points);
```

In the text, no need to say in which function we are, or to write that the number of points is zero, or to put a `\n`, all this is done automatically.

Error management rules in `class`

Rule 5:

Always allocate memory with the macros `class_alloc()`, `class_calloc()`, `class_realloc()`.

Instead of

```
malloc(parray, N*sizeof(double));
```

use

```
class_alloc(parray, N*sizeof(double), pxx->error_message);
```

If allocation fails (N too big, null or negative), the function will automatically return a `_FAILURE_` and the code will return an appropriate error message:

```
Error running background_init
=>background_init(L:537):error in background_solve(ppr,pba);
=>background_solve(L:1303):could not allocate pvecback with
    size -8
```

Error management rules in `class`

Useful `CLASS` macros:

```
class_call(function, errmsg_input, errmsg_output);  
class_call_parallel(...);  
class_call_except(...,[line of code;line of code;...]);  
  
class_test(condition, errmsg_output, "message" [,args]);  
class_test_parallel(...);  
class_test_except(...,[line of code;line of code;...]);  
class_stop(errmsg_ouput, "message" [,args]);  
  
class_alloc(pointer, size);  
class_alloc_parallel(...);  
class_realloc(...);  
class_calloc(...);
```



You can see them in `include/common.h` files!

Error management rules in `class`

Few special cases:

- in `main/class.c` there is no “higher level” so the 10 initialisation functions are called like e.g.:

```
int main(int argc, char **argv) {
    if (background_init(&pr,&ba) == _FAILURE_) {
        printf("\n\nError running background_init \n=>%s\n"
            ,ba.error_message);
        return _FAILURE_;
    }
}
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    }
}
```

- the input module does not have an error message attached to its structure, and just uses the local variable `errmsg`. So inside this module, the calls read e.g.:

```
class_call(background_ncdm_init(ppr,pba),
            pba->error_message,
            errmsg);
class_call(parser_read_file(...,errmsg),
            errmsg,
            errmsg);
```


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}
```

- the input module does not have an error message attached to its structure, and just uses the local variable `errmsg`. So inside this module, the calls read e.g.:

```
class_call(background_ncdm_init(ppr,pba),
            pba->error_message,
            errmsg);
class_call(parser_read_file(...,errmsg),
            errmsg,
            errmsg);
```

- when calling external functions not in the 10 modules we must pass the error message as an argument:

```
class_call(array_interpolate(...,pba->error_message),
            pba->error_message,
            pba->error_message);
```

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- 5 change `fld` into `earde`
- 6 change some equations to describe the specific properties of your feature