

CLASS

the Cosmological Linear Anisotropy Solving System¹



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¹ code developed by Julien Lesgourgues & Thomas Tram plus many others

Lecture 3: coding with `class`

- ① overall structure of `class`
- ② dynamical indexing rules
- ③ input parameters
- ④ error management rules
- ⑤ adding features
- ⑥ adding parameters in the wrapper
- ⑦ interface with samplers

Overall structure of `class`

In CLASS, what is a `module`?

- a file `include/xxx.h` containing some declarations
- a file `source/xxx.c` containing some functions
- each module is associated with a structure `xx`, containing all what *other* modules need to know, and nothing else
- some fields in this structure are filled in the `input.c` module (input parameters relevant for this module)
- all other fields are filled by a function `xxx_init(...)`
- “executing a module” \equiv calling `xxx_init(...)`



In `include/background.h`: localise `struct background`
In `source/background.c`: localise `background_init()`

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--------	-----------	-----	---	--------------

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output.c	output	op	pop	description of output format

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Each module contains:

- a function `xxx_init(...)` filling the structure `xx`
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- some functions `xxx_external_1(...)`, ..., `xxx_external_n(...)` that can be called from other modules (e.g. to read correctly or interpolate the content of the structure `xx`)
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Following order always respected in `xxx.c`:

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Remark: a module in the `CLASS` code is very similar to a “class” in C++. We enjoy the structure of C++ with the speed and readability of C.

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Count number of external and internal functions in
`source/background.c`:

Search “`int background_`” starting from top

Overall structure of `class`

The `main()` function of `CLASS` located in `main/class.c` could only contain:

```
int main() {
    input_init_..(..,ppr,pba,pth,ppt,ptr,ppm,psp,pnl,ple,pop);
    background_init(ppr,pba);
    thermodynamics_init(ppr,pba,pth);
    perturb_init(ppr,pba,pth,ppt);
    primordial_init(ppr,ppt,ppm);
    nonlinear_init(ppr,pba,pth,ppt,ppm,pnl);
    transfer_init(ppr,pba,pth,ppt,pnl,ptr);
    spectra_init(ppr,pba,ppt,ppm,pnl,ptr,psp);
    lensing_init(ppr,ppt,psp,pnl,ple);
    output_init(pba,pth,ppt,ppm,ptr,psp,pnl,ple,pop)
    /* all calculations done, free the structures */
    lensing_free(ple);
    spectra_free(psp);
    transfer_free(ptr);
    nonlinear_free(pnl);
    primordial_free(ppm);
    perturb_free(ppt);
    thermodynamics_free(pth);
    background_free(pba);
}
```

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- We choose an abbreviation of 2 letters for these indices, `_bg_`.
- Then we declare all possible indices `index_bg_<blabla>` in `include/background.h` (more precisely, inside the structure `background`, because these indices are necessary for manipulating the background table).

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- Then we declare all possible indices `index_bg_<blabla>` in `include/background.h` (more precisely, inside the structure `background`, because these indices are necessary for manipulating the background table).
- We also declare `flags` saying whether these indices need to be defined or not.

Dynamical indexing rules in `class`

In `include/background.h`:

```
struct background {  
    /** input parameters with assigned in the input module*  
    */  
    double Omega0_cdm;  
    ...  
    /** flags and indices */  
    int has_cdm;      // can take values _TRUE_ or _FALSE_  
    ....  
  
    int index_bg_rho_cdm;  
    ...  
  
    int bg_size;  
  
    /** interpolation table */  
    double * background_table;  
}
```

Dynamical indexing rules in `class`

In `source/background.c`, the function `background_indices()` called at the beginning of `background_init()` assigns numerical value to indices, that the user will never need to know (quantities always written symbolically as `y[pba->index_bg_rho_cdm]`)

```
int background_indices(pba,...) {
    /* initialize all flags */
    if (pba->Omega0_cdm != 0.)
        pba->has_cdm = _TRUE_;
    ...
    /* initialize all indices */
    index_bg=0;
    class_define_index(pba->index_bg_rho_cdm,
                      pba->has_cdm,
                      index_bg,
                      1);
    class_define_index(pba->index_bg_rho_fld,
                      pba->has_fld,
                      index_bg,
                      1);
    ...
    pba->bg_size = index_bg;
}
```

Dynamical indexing rules in `class`

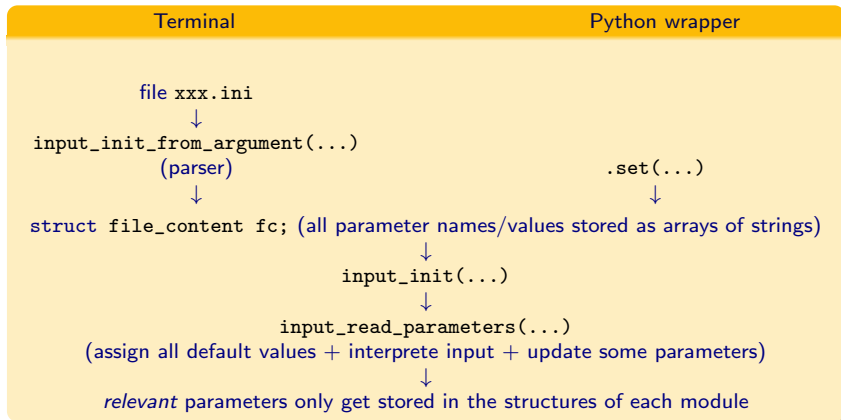
This logic is followed everywhere for all groups of indices! Examples:

- in `background.c`: `index_bg_...` for all background variables
- in `background.c`: `index_bi_...` subset of backg. var. integrated over time
- in `thermodynamics.c`: `index_th_...` for all thermodynamics variables
- in `perturbations.c`: `index_pt_...` perturbation var. integrated over time
- in `perturbations.c`: `index_mt_...` metric perturbations
- in `perturbations.c`: `index_md_...` list of modes (scalar, vector, tensor)
- in `perturbations.c`: `index_ic_...` list of initial conditions (AD, CDI, NID...)
- in `perturbations.c`: `index_tp_...` list of type of required source
(temperature, polarisation, matter fluctuation...)
- in `perturbations.c`: `index_ap_...` list of approximations that may be used
- etc. etc.



Check in your `include/*.h` files!

Input management in `class`



For special parameters requiring a **shooting method**: repeated calls of `input_read_parameters(...)` from `input_init(...)` until shooting target is met.

Input management in `class`

For normal parameters (no shooting): example of CDM density:

```
/** -  $\Omega_{0\_cdm}$  (CDM) */
class_call(parser_read_double(pfc,"Omega_cdm",&param1,&
    flag1,errmsg),
    errmsg,
    errmsg);
class_call(parser_read_double(pfc,"omega_cdm",&param2,&
    flag2,errmsg),
    errmsg,
    errmsg);
class_test(((flag1 == _TRUE_) && (flag2 == _TRUE_)),
    errmsg,
    "In input file, you can only enter one of
    Omega_cdm or omega_cdm, choose one");
if (flag1 == _TRUE_)
    pba->Omega0_cdm = param1;
if (flag2 == _TRUE_)
    pba->Omega0_cdm = param2/pba->h/pba->h;
```

Input management in `class`

For `shooting` parameters, establish mapping between *target parameter*, *unknown parameter* and *level*. Currently:

target parameter	unknown parameter	level
$100 \times \theta_s$	h	thermodynamics
σ_8	A_s	spectra
Ω_{dcdm}	$\rho_{\text{dcdm}}^{\text{ini}}$	background
...

... plus a few others (alternative parametrizations of decaying CDM, quintessence parameters).

If you need to add such parameters: see how it is done e.g. for `100*theta_s` and replicate the structure!

Error management rules in `class`



Run with an input file containing only

```
omega_b = 0.07
```

Error management rules in class

By following a few general rules, we get automatically some very informative error messages like:

```
Error in thermodynamics_init
=>thermodynamics_init(L:292) :error in
    thermodynamics_helium_from_bbn(ppr,pba,pth);
=>thermodynamics_helium_from_bbn(L:1031) :condition (omega_b
    > omegab[num_omegab-1]) is true; You have asked for an
    unrealistic high value omega_b = 7.e-02. The
    corresponding value of the primordial helium fraction
    cannot be found in the interpolation table. If you
    really want this value, you should fix YHe to a given
    value rather than to BBN
```

We only wrote the piece starting with “You have asked...”. All the rest was generated automatically by the code. This follows from following everywhere 5 rules.

Error management rules in `class`

Rule 1:

All functions are of type `int`, and return either `_SUCCESS_` or `_FAILURE_` (defined internally in `include/common.h`: `#define _SUCCESS_ 0` , `#define _FAILURE_ 1`)

```
int function(input, &output) {  
    ...  
    if (something goes wrong) return _FAILURE_;  
    ...  
    return _SUCCESS_;  
}
```

Error management rules in `class`

Rule 2:

All functions are called with the macro `class_call(...)` (all macros `class_xxx(...)` are defined in `include/common.h`):

```
class_call(function(input, &output),  
            error_message_from_function,  
            error_message_output);
```

This is simply a short-cut for

```
if (function == _FAILURE_) {  
    ErrorMsg Transmit_Error_Message;  
    sprintf(Transmit_Error_Message, "%s(L:%d) : error in %s;\n",  
            n=>%s", __func__, __LINE__, #function,  
            error_message_from_function);  
    sprintf(error_message_output, "%s", Transmit_Error_Message  
            );  
    return _FAILURE_;  
}
```

Error management rules in `class`

Rule 3:

Each of the 9 main structures `xx` has a field called `error_message`. Any function in the module `xxx.c` is called `xxx_something()` and writes its error message in `xx.error_message` (if `pxx` is a pointer to `xx`, in `pxx->error_message`).

So if we are in `perturb_init()` and we call `perturb_indices()` we write:

```
class_call(perturb_indices(...,ppt),
           ppt->error_message,
           ppt->error_message);
```

But if we are in `perturb_init()` and we call `background_at_tau()` we write:

```
class_call(background_at_tau(...,pba),
           pba->error_message,
           ppt->error_message);
```

Error management rules in `class`

Rule 4:

Whenever an error could occur, we first write a test with the macro

`class_test(.,.,.)`:

```
class_test(condition, error_message, "Some text");
```

or

```
class_test(condition, error_message, "Some text and numbers  
%d %e",n,x);
```

Example:

```
class_test(num_points == 0,  
           ppt->error_message,  
           "this might be caused by ...");  
step = (max-min)/((double)num_points);
```

In the text, no need to say in which function we are, or to write that the number of points is zero, or to put a `\n`, all this is done automatically.

Error management rules in `class`

Rule 5:

Always allocate memory with the macros `class_alloc()`, `class_calloc()`, `class_realloc()`.

Instead of

```
malloc(parray, N*sizeof(double));
```

use

```
class_alloc(parray, N*sizeof(double), pxx->error_message);
```

If allocation fails (N too big, null or negative), the function will automatically return a `_FAILURE_` and the code will return an appropriate error message:

```
Error running background_init
=>background_init(L:537):error in background_solve(ppr,pba);
=>background_solve(L:1303):could not allocate pvecback with
    size -8
```

Error management rules in `class`

Useful `CLASS` macros:

```
class_call(function, errmsg_input, errmsg_output);
class_call_parallel(...);
class_call_except(...,[line of code;line of code;...]);

class_test(condition, errmsg_output, "message"[,args]);
class_test_parallel(...);
class_test_except(...,[line of code;line of code;...]);
class_stop(errmsg_output, "message"[,args]);

class_alloc(pointer, size);
class_alloc_parallel(...);
class_realloc(...);
class_calloc(...);
```



You can see them in `include/common.h` files!

Error management rules in `class`

Few special cases:

- in `main/class.c` there is no “higher level” so the 10 initialisation functions are called like e.g.:

```
int main(int argc, char **argv) {
    if (background_init(&pr,&ba) == _FAILURE_) {
        printf("\n\nError running background_init \n=>%s\n"
            ,ba.error_message);
        return _FAILURE_;
    }
}
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        return _FAILURE_;
    }
}
```

- the input module does not have an error message attached to its structure, and just uses the local variable `errmsg`. So inside this module, the calls read e.g.:

```
class_call(background_ncdm_init(ppr,pba),
            pba->error_message,
            errmsg);
class_call(parser_read_file(...,errmsg),
            errmsg,
            errmsg);
```

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int main(int argc, char **argv) {
    if (background_init(&pr,&ba) == _FAILURE_) {
        printf("\n\nError running background_init \n=>%s\n"
            ,ba.error_message);
        return _FAILURE_;
    }
}
```

- the input module does not have an error message attached to its structure, and just uses the local variable errmsg. So inside this module, the calls read e.g.:

```
class_call(background_ncdm_init(ppr,pba),
            pba->error_message,
            errmsg);
class_call(parser_read_file(...,errmsg),
            errmsg,
            errmsg);
```

- when calling external functions not in the 10 modules we must pass the error message as an argument:

```
class_call(array_interpolate(...,pba->error_message),
            pba->error_message,
            pba->error_message);
```

Implementing new features `class`

If you want to implement:

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- a new mathematical description of an existing species (switching on more precise corrections, etc.)
- a new observable or output (new source function, new transfer function, new spectrum...)

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- 4 duplicate these occurrences
- 5 change `fld` into `earde`
- 6 change some equations to describe the specific properties of your feature

Adding parameters in the wrapper

Example of python wrapper:

```
# redeclaration of relevant CLASS variables in cython
python/cclassy.pxd
# wrapper's function (.set(), .compute(), .lensed_cl(), ...)
python/classy.py
```

Don't edit any other! (generated automatically at compilation, or for testing or module installation)

Adding parameters in the wrapper

In python/cclassy.pxd relevant variables redeclared inside the structure to which they belong:

```
cdef struct background:
    ...
    double age
    ...
cdef struct thermo
    ...
    double z_reio
    ...
```

Indeed, in the C code, pba->age, pth->z_reio exist...

When defining new parameter in C code that should be accessible from outside: redeclare them here!

Adding parameters in the wrapper

E.g.: new model of Presidential Dark Matter.

In `include/background.h`:

```
struct background{  
    ...  
    double rho_trump;  
    ...  
}
```

In `python/cclassy.pxd`:

```
cdef struct background:  
    ...  
    double rho_trump  
    ...
```

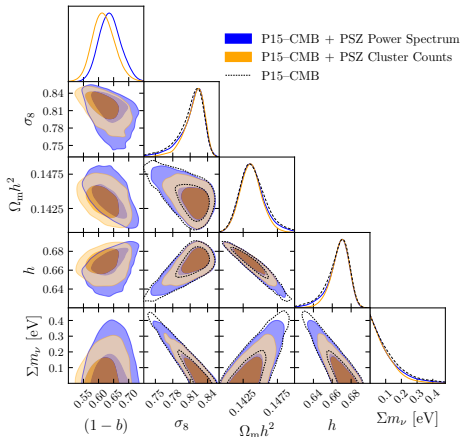
Recompile after a `make clean` !

Interface with sampler

Many are compatible with CLASS! Non-exhaustive list:

- Bayesian samplers:

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Bolliet et al. 2019

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At least in MontePython, Cobaya and CAMEL: no declaration of cosmological parameters in the sampler! No need to modify anything if you add new parameters! (whatever parameter `'name'` read in input file just passed directly through `class.set('name',...)`)